## **Dynamics of Economic Networks**

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### **Economic Networks**

- ... one example (from Amadeus database)
  - networks reflect structure of economic control
- some types of economic networks:
  - ownership networks between firms (investments)
  - networks of board members of firms (decisions)
  - R& D networks (transfer of knowledge)
  - supply networks (transfer of goods)
  - credit networks (transfer of risk)

### Download Tools for Network Vizualization (M. Geipel)

from our homepage www.sg.ethz.ch/research/graphlayout



### **Ownership Networks and Geography**

• how does geography impact the structure of ownership control?



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# **Economic Networks**

- consist of nodes ( $\Rightarrow$  firms) and links ( $\Rightarrow$  interactions)
- Physics perspective: focus on the links
  - topological features, degree distribution, path length
  - centrality, modularity, clustering, cliquishness, ...
  - dynamics (preferential attachment)
- Economics perspective: focus on links and nodes
  - eigendynamics of nodes (e.g. growth, R&D, entry/exit)
  - eigendynamics of links (adaptation, creation/removal)
  - different time scales of link and node dynamics
  - quality of links (unidirectional, weight, costs)
  - feedback of links on the node dynamics
  - utility maximization vs. boundedly rational behavior



# **Costs and benefits**

- economic system: large number of interacting agents
- agent *i*: *utility* from economic interaction with agents *j*:

$$ext{utility}_i(t) = \sum_j ext{benefits}_{ij}(t) - ext{costs}_{ij}(t)$$

▶ aim: (i) increase benefits, (ii) reduce costs, (iii) do both

### benefits:

- reach a common goal (optimal use of resources)
- exchange of knowledge (R&D network)

#### osts:

- exploration costs (search for partners)
- transaction costs (costs for interaction)
- friction from differences in 'behavior', 'opinion', ...
- costs for maintenance of connections
- (indirect: 'dissipation', 'saturation')



# **Application: Emergence of Local Cultures**

- economics: localized producer networks (clusters)
  - ▶ need of a shared understanding on what constitutes acceptable business practice ⇒ *local cultures* (= social norms)
- benefits of local cultures
  - avoid coordination dilemma among firms (alignment of quantities produced, investment incentives for research and training)
  - $\Rightarrow\,$  foster positive externalities: knowledge spillovers, pooled labour markets
- existing studies: game theoretic analysis
  - require "known" optimum behaviour and a notion of "oughtness" for co-operation
- our model: investigates which behaviour comes to be shared
  - ▶ no ex-ante best behaviour (many strategies  $\rightarrow$  business success)

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Bounded confidence model

### Convergence toward shared behavior

agent i: 'economic' behavior  $x_i(t) \in [0,...,1]$ 

assumption: utility increases if everyone shares same behavior

• benefit: b = const., costs:  $\sim \Delta x$ 

 $u_i(t) = \sum_j b - c |x_i - x_j|$ 

**2** assumption: interaction ij occurs only iff  $u_{ij}(t) > u_{thr}$ 

 $|x_i - x_j| < \varepsilon = (b - u_{\mathrm{thr}})/c$ 

- $\blacktriangleright$  possibility of interaction depends on 'open-mindedness'  $\varepsilon$
- bounded confidence model (Deffuant et al., 2000)

assumption: interaction leads to more similar behavior

 $x_i(t+1) = x_i(t) + \mu [x_j(t) - x_i(t)]$  $x_j(t+1) = x_j(t) + \mu [x_i(t) - x_j(t)]$ 

•  $\mu = 0.5$ : both agents adopt the 'mean' behavior

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Influence of emerging in-groups

# Influence of emerging in-groups

- interacting agents added to each other's in-group  $I_i$  and  $I_j$ 
  - partnership relations from past interactions
- evidence that in-groups constrain agent behaviour
  - game theory (Fehr & Fischerbacher 2004)
  - group theory (French 1956, Lehrer 1956, Wagner 1978)
  - social impact theory (Latané 1981, Latané & Nowak 1997)
- influence of *emerging in-groups* on agent's *i* behaviour x<sub>i</sub>?
  - effective behaviour  $x_i^{\text{eff}}$  considers mean in-group behaviour  $x_i^I$

 $x_i^{\text{eff}} = (1 - \alpha_i)x_i + \alpha_i x_i^{I}$ 

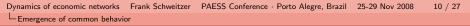
- group influence  $\alpha_i$  increases with group size
- permanent influence of in-group on interaction:  $\left|x_{i}^{\text{eff}}-x_{i}^{\text{eff}}\right|<\varepsilon$ 
  - $\blacktriangleright$  search for new partners is costly  $\rightarrow$  keep past partners
  - keep behavior close to past partners to allow further interaction



## Co-evolution of economic network and behavior

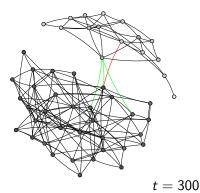
- randomly choose agents i, j at time t
- Iink dynamics (considers existing in-group)
  - $\Delta x^{\text{eff}}(t) < \varepsilon \Rightarrow$  link formation (interaction)
  - $\Delta x^{\text{eff}}(t) > \varepsilon \Rightarrow$  no link created or *existing link is removed*
- **Q** dynamics in individual behavior (considers  $x_i(t)$ ,  $x_j(t)$ )
  - interacting agents become more similar
- adjustment of effective behavior
  - agent  $i, j: x_i \to x_i^{\text{eff}}, x_j \to x_j^{\text{eff}}$
  - ▶ in-groups of *i* and *j*:  $x_i^{\text{eff}}$ ,  $x_i^{\text{eff}}$  affected by changed  $x^{l_i(t)}$ ,  $x^{l_j(t)}$

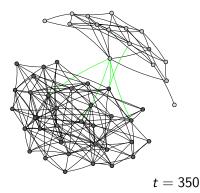
**Result:** feedback between agents' behavior and their in-group structure  $\Rightarrow$  Computer simulation



Results of computer simulations

### Group Influence: two nearly separated components...





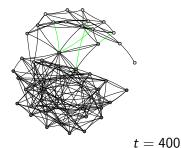
• 50 agents,  $\varepsilon = 0.3$ 

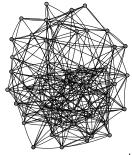
- green link: agents would not interact without group influence
- red link: agents would not interact anymore

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### ... finally united





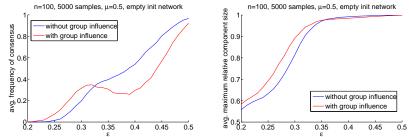
t = 500

- group influence (on average and a large range of  $\varepsilon$ )
  - fosters coalescence of components
  - increases maximum component size
  - ⇒ consensus toward a common behavior



#### Influence of interaction costs on behavioral consensus?

large costs  $\Leftrightarrow$  small 'open-mindedness'  $\varepsilon = (b - u^{\text{thr}})/c)$ 



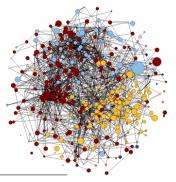
• large costs ( $0 < \varepsilon < 1/3$ )

in-group influence increases probability to reach consensus

- size of largest component increases
- small costs (1/3  $< \varepsilon < 1/2$ )
  - with in-group influence, consensus becomes less probable
  - but size of largest component is not affected by in-group influence

## **Application: Innovation Networks**

- complex technologies  $\Rightarrow$  firms must rely on knowledge transfers
  - ► Recent studies: relationship/performance of existing R&D networks
  - emergence of R&D networks, not just on existing networks



Picture from NEMO: Network Models, Governance and R&D collaboration networks, www.nemo-net.eu

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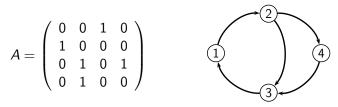
Model outline: agent dynamics

## Costs and benefits in knowledge exchange

• agent *i*: knowledge stock  $x_i(t) > 0$ , knowledge growth:

 $\frac{dx_i}{dt} = B_i(\mathbf{A}, \mathbf{x}) - C_i(\mathbf{A}, \mathbf{x})$ 

- ▶ interaction (e.g. R&D collaborations)  $\Rightarrow$  adjacency matrix **A**
- $B_i(\mathbf{A}, \mathbf{x})$ : benefits (knowledge spillovers)  $\Rightarrow \dot{x}_i = \sum_{i=1}^n a_{ij} x_j$
- $C_i(\mathbf{A}, \mathbf{x})$ : costs of collaborations ~ number of links  $d_i$



agent's 'profit' over certain time period: u<sub>i</sub>(t) = λ<sub>PF</sub> − cd<sub>i</sub>
 λ<sub>PF</sub> = lim<sub>t→∞</sub> x<sub>i</sub>/x<sub>i</sub>: largest real (Perron-Frobenius) eigenvalue of A

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Model outline: link dynamics

# Evolution of the economic network

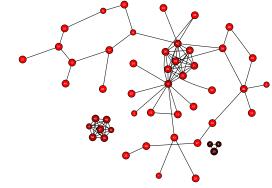
- Problem of maximizing u<sub>i</sub>: optimize collaborations (→ λ<sub>PF</sub>), network structure (d<sub>i</sub>) ⇒ minimize costs (~ c)
- network dynamics: (initialization: empty graph)
- **1 quasi-equilibrium**: fast knowledge growth **A** fixed  $\rightarrow$  profits  $u_i$  reach balanced growth
- **2** perturbation of network: pair of agents (i, j) is selected at random
  - ▶ link  $ij \notin E(G)$  is created if
    - ★ either u<sub>i</sub> or u<sub>j</sub> is increased and none of u<sub>i</sub> and u<sub>j</sub> is decreased (incremental improvement)
  - link  $ij \in E(G)$  is deleted if
    - ★ at least one agent gains from the change (asymmetry!) link deletion involves severance cost:  $v(\alpha, c) = (1 - \alpha)c$  with  $\alpha = c'/c$  $\alpha \in [0, 1]$ :  $\alpha = 0$ : full loss of investment,  $\alpha = 1$ : no loss
- ${f 3}$  stop if network is pairwise stable, otherwise go to  ${f 1}$



Model outline: link dynamics

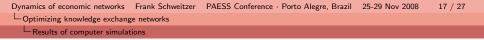
### **Example: Equilibrium network for** $\alpha = 0.0$

- heterogeneous degree distribution (hubs), giant component
- high severance cost prevent agents from further deleting links
- pairwise stability  $\neq$  efficiency (suboptimal solution)



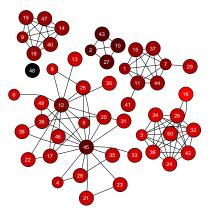
n = 50, c = 0.15, darker colours  $\rightarrow$  higher profits

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### **Example: Equilibrium network for** $\alpha = 0.2$

stronger clustering, disconnected components

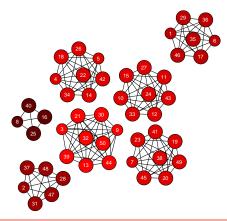






### **Example: Equilibrium network for** $\alpha = 1.0$

• the smaller severence costs (loss after reconfiguration), the larger the tendency to form disconnected cliques (fully connected groups)

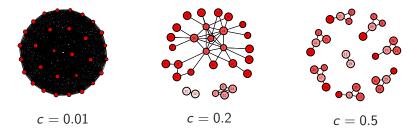






### Simulations: Growing Networks with $\alpha = 0$

intial setting: empty graph ⇒ final setting: equilibrium network
0 < c < 0.5: fully connected graph is efficient network</li>



- equilibrium networks more sparse and clustered with increasing c
- inefficient equilibrium networks are reached
  - for given cost, multiple equilibria exist
  - equilibrium network is path dependent (stochastic influences)

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Knowledge Growth with Quadratic Costs

# Knowledge Growth with Quadratic Costs

node dynamics

$$\frac{dx_i}{dt} = -dx_i + b\sum_{i=1}^n a_{ji}x_j - c\sum_{i=1}^n a_{ij}x_i^2$$

- network dynamics:
  - pair of agents, i and j, is selected at random
  - different agent strategies
    - ★ unilateral link deletion/creation ⇒ indirect reciprocity
    - ★ bilateral link deletion/creation ⇒ direct reciprocity
  - decision are bounded rational
    - \* locally bounded (no complete information on the system)
    - \* temporarily bounded (finite time horizon)

M. König, S. Battiston, F. Schweitzer: Modeling Evolving Innovation Networks, in: Innovation Networks – New Approaches in Modeling and Analyzing (Eds. A. Pyka, A. Scharnhorst), Springer (2007)

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Baseline case

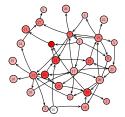
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#### Baseline case: linear benefit and null costs

node dynamics

$$\frac{dx_i}{dt} = -dx_i + \sum_{i=1}^n a_{ji}x_j$$

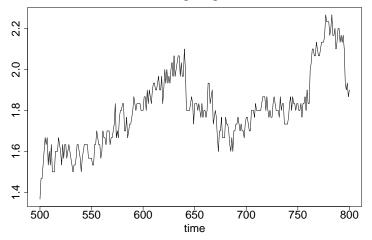
 network dynamics: initial *random* network, remov least fit node, replacement with random links



- emergence of a core of *cooperative* firms, and a *parasitic* pheriphery
- considerable crashes and recovery



average degree



#### • considerable crashes and recovery

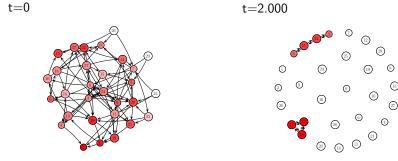
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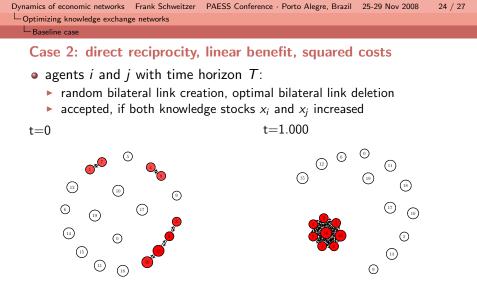
Baseline case

Case 1: indirect Reciprocity, linear benefit, squared costs

- agent *i* with time horizon *T*:
  - random unilateral link creation, optimal unilateral link deletion
  - accepted, if knowledge stock x<sub>i</sub> increased



initial links break down in favour of few bilateral cooperationsfree-riders get isolated



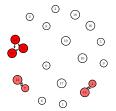
- initially connected agents evolve towards fully connected network
   initially isolated agents have nothing to contribute
- initially isolated agents have nothing to contribute

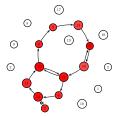
Dynamics of economic networks Frank Schweitzer PAESS Conference · Porto Alegre, Brazil 25-29 Nov 2008 25 / 27 Optimizing knowledge exchange networks

Baseline case

Case 3: ind. reciprocity, weighted linear benefit, squared costs

$$\frac{dx_i}{dt} = -dx_i + b\sum_{i=1}^n a_{ji}x_j + b_{ext}\sum_{i=1}^n w_{ji}x_j - c\sum_{i=1}^n a_{ij}x_i^2$$
• externalities: higher weights to
• links providing shorter paths (Jackson, Watts 2002)
• links contributing to cycles  $\Rightarrow$  feedback on technology
t=500
t=500





cyclic externalities support emergence of indirect reciprocity

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# Conclusions

- important aspect of economic networks: link and node dynamics
- example 1: formation of local cultures (~ social norm)
  - common behavior reduces costs of interaction (friction, risk of failure)
  - $\blacktriangleright$  in-group evolves  $\rightarrow$  modifies firms behavior  $\rightarrow$  feeds back to interaction, economic network
  - decreasing c does not increase probability of (full) consensus
- example 2: innovation networks
  - ► linear/nonlinear cost functions ⇒ limits for connected networks
  - multiple equilibria: many stable, but inefficient equilibrium networks
  - different agent strategies for link creation/removal
  - ▶ if severance costs grow, agents stick to their suboptimal solutions
  - both analytical results and computer simulations

#### This research overview is based on the publications:

- P. Groeber, F. Schweitzer, K. Press: How groups can foster consensus: The case of local cultures, J. Artificial Societies and Social Simulations (2008, submitted)
- M. Koenig, S. Battiston, M. Napoletano, F. Schweitzer: The efficiency and evolution of R&D networks, *J. Economic Dynamics and Control* (2008, submitted)
- M. D. König, S. Battiston, M. Napoletano, F. Schweitzer: On Algebraic Graph Theory and the Dynamics of Innovation Networks, *Networks and Heterogeneous Media* Vol. 3, Num. 2, June 2008, http://arxiv.org/abs/0712.2752
- M. D. König, S. Battiston, F. Schweitzer: Modeling Evolving Innovation Networks, in: *Innovation Networks - New Approaches in Modeling and Analyzing* (Eds. A. Pyka, A. Scharnhorst), Heidelberg: Springer (2008, forthcoming), http://arxiv.org/abs/0712.2779
- further publications: http://www.sg.ethz.ch/publications/